300DPI High-Speed Contact Image Sensor Module

Description

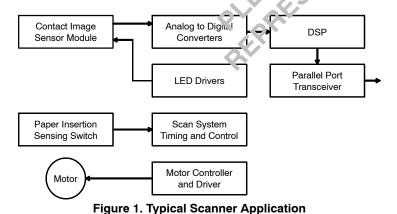
The NOM03A6–AY17G contact image sensor (CIS) module integrates a yellow LED light source with reflector, lens and image sensor in a compact housing. The module is designed for document scanning, mark reading, gaming and office automation equipment applications and is suitable for scanning documents up to 104 mm wide. An analog video output achieves a scanning rate of 250 µsec/line. The NOM03A6–AY17G module employs proprietary CMOS image sensing technology from ON Semiconductor to achieve high–speed performance and high sensitivity.

Features

- Light Source, Lens and Sensor are Integrated Into a Sing' Mod
- 104 mm Scanning Width at 11.8 dots per mm Resolution
- 250 µsec/Line Scanning Speed @ 5.0 MHz Pixel Rate
- Analog Video Output
- Supports A6 Paper Size at up to 138 Pager "null
- Yellow LED Light Source with Reflecto
- Wide Dynamic Range
- Compact 119.7 mm x 19.0 mm 13./ mm 1. Housing
- Low Power
- Light Weight 1.1 oz Pack
- These Devices are Pb ree. en rree/BFR Free and are Rous Compliant

Applications

- Ticket, Chec and Car Scanners
- Receipt Scan s
- · Mark Readers
- Office Automation Equipment





ON Semiconductor®

http://onsemi.com



IMAGE SENSOR MODULE A6
CASE MODAF

MARKING DIAGRAM

NOM03A6-AY17G YYMMSSSSSS

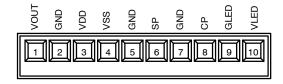
YY = Year

MM = Month

SSSSSS = Serial Number

G = Pb-Free Package

CONNECTOR PIN ASSIGNMENT



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 2 of this data sheet.

Table 1. ORDERING INFORMATION

Part Number	Package	Shipping Configuration
NOM03A6-AY17G	(Pb-free)	100 per packing carton

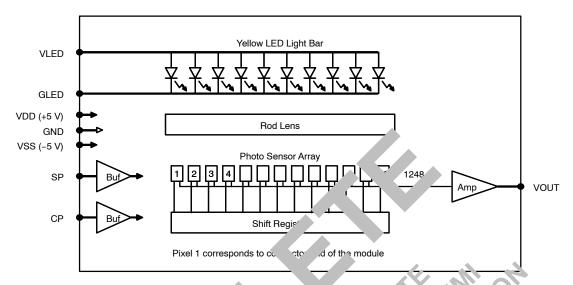


Figure 2 implified Bi Jk Diagram

Table 2. PIN FUNCTION DESCRIPTION

Pin	Pin Name	L'escription
1	VOUT	Analic Video ut
2	GND	Chauna
3	VDD	+5 vei July
4	VSS	V to 2 V power supr v
5		CO CHAIN
6	SP	Shift register start, rulse
7	ND	Ground
8	Cr	Sampling clock pulce
9	GLED	Ground for the CD light SOU ce
10	VLED	Power sur or your that Fullight source

Table 3. ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Power supply voltage	V _{DD}	7	V
	V _{SS}	-15	V
	V _{LED}	6	V
Power supply current	I _{LED}	450	mA
Input voltage range for SP, CP	V _{in}	-0.5 to V _{DD} + 0.5	V
Storage Temperature	T _{STG}	-20 to 75	°C
Storage Humidity, Non-Condensing	H _{STG}	10 to 90	%
ESD Capability, Contact Discharge (Note 1)	ESD _{HBM}	±2	kV

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are ess ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses about the Fourth-simmended Operating Conditions may affect device reliability.

Table 4. RECOMMENDED OPERATING RANGES (Unless other vise spec d, these specifications apply T_A = 25°C) (Note 2)

Parameter	Sym	Min	Тур	Max	Unit
Power supply voltage (Note 3)	V _L	5	5	5.5	V
	V _{SS}	-12	- 5	4.5	V
	V _{LED}	4.5	5	5.5	V
Power supply current		20	30	40	mA
	Iss	55	6	7	mA
	I _{LED}	250	30 0	350	mA
Low level input voltage for SP, CP	V _{IL} C	10	0	0.8	V
High level input voltage for SP, CP	V ₀₁	4.5	5.0	V _{DD} + 0.3	V
Line scanning rate (Note 4)	T _{int}	227	250	624	μs
Clock frequency (Note 5)	T .	2.0	5.0	5.5	MHz
Clock period		182	200	500	ns
Clock pulse wir (Note 6,	t _w	46	50	125	ns
Clock pulse hig. ıty cycle	P Con	20	25	60	%
Start pulse width (No.	'wSP	150	180	480	ns
Start pulse setup time	t _{su}	20			ns
Start pulse hold time	t _h	20			ns
Prohibit crossing time (Note 7)	t _{prh}	20			ns
Clock to Video output propagation delay ris, r	t _{pcor}	115			ns
Clock to Video output propagation delay falling	t _{pcof}	20			ns
Operating Temperature	T _{op}	0		50	°C
Operating Humidity, Non-Condensing	H _{op}	10		60	%

^{1.} This module assembly has been ESD tested to IEC61000-4-2 (HBM) Conta Jischa

Refer to Figure 3 for more information on AC characteristics
 V_{LED} directly affects illumination intensity, which directly affects V_{OUT}.
 T_{int} is the line scanning rate or integration time. T_{int} is determined by the interval between two start pulses. The clock is proportional to T_{int}.
 Main clock frequency (f) corresponds to the video sampling frequency.

^{6.} Min, Typ, Max specifications reflect operation at the corresponding Min, Typ, Max clock frequency.

^{7.} Prohibit crossing time is to insure that two start pulses are not supplied in the same scan line time. SP may only be active high during one falling edge of CP for any given scan.

Table 5. PHYSICAL SPECIFICATIONS

Parameter	Symbol	Тур	Unit
Scan width	PD_{w}	104	mm
Number of Photo Detector Arrays	PDA _n	13	arrays
Number of Photo Detectors	PD_n	1248	elements

Table 6. PHYSICAL CHARACTERISTICS

Parameter	Symbol	Min	Тур	Max	Unit
Pixel pitch	PD _{sp}		84.7		μ m
Inter-array spacing	PDA _{sp}	150	180	210	μ m
Inter-array vertical alignment	PDA _{vxp}	-40	0	40	μ m
Yellow LED peak wavelength	λ_{p}	596	5"5	581	nm

Table 7. ELECTRO-OPTICAL CHARACTERISTICS TEST CON., ITIC.

Parameter	Sym ^t	Value	Unit
Power supply voltage		5.0	V
	V _{LED}	5.0	V
Clock frequency	f	5.0	MHz
Clock pulse high duty cycle	70	2E	%
Line scanning rate	int	250	μs
LED arrays pulsed time on (Note 8)	LED_Ton	25	ms
LED arrays pulsed time off (Note 8)	LED_Toff	356	ms
Operating Temperature	T _{rp}	25	°C
Operating Temperature 3. Production tested with pulsion Ds.	CORATIVE		

^{8.} Production tested with pulsi-

Table 8. ELECTRO-OPTICAL CHARACTERISTICS (Unless otherwise specified, these specifications were achieved with the test conditions defined in Table 7)

Parameter	Symbol	Min	Тур	Max	Unit
Bright analog output voltage (Note 9)	V_{pavg}	0.9	1.0	1.1	V
Bright output non-uniformity (Note 10)	U _p	-30		30	%
Bright output non-uniformity total (Note 11)	U _{ptotal}			60	%
Adjacent pixel non-uniformity (Note 12)	U_{padj}			25	%
Dark output voltage (Note 13)	V_d			200	mV
Dark non-uniformity (Note 14)	U _d			75	mV
Modulation transfer function at 75 line pairs per in (lp/in) (Note 15)	MTF ₇₅	30			%
Modulation transfer function at 150 line pairs per in (lp/in) (Notes 15, 16)	MTF ₁₅₀	15			%

9. $V_{pavg} = \sum V_{p(n)}/1248$, where V_p is the pixel amplitude value of V_{OUT} for a bright signal defined as a white do. vith LFDs turned on,

n is the sequential pixel number in one scan line.

 $10.U_p = \frac{1}{V_{pmax} - V_{pavg}} \frac{100\%, \text{ or } [V_{pavg} - V_{pmin})}{V_{pmax}} \times 100\%, \text{ whin}$ $V_{pmax} = \frac{1}{V_{pmax}} \frac{100\%, \text{ or } [V_{pavg} - V_{pmin})}{V_{pmax}} \times 100\%, \text{ whin}$ $V_{pmax} = \frac{1}{V_{pmax}} \frac{1}{V_{pmax}} \times 100\%, \text{ or } [V_{pavg} - V_{pmin}) \times 100\%, \text{ whin}$ $V_{pmax} = \frac{1}{V_{pmax}} \frac{1}{V_{pmax}} \times 100\%, \text{ or } [V_{pavg} - V_{pmin}) \times 100\%, \text{ whin}$ $V_{pmax} = \frac{1}{V_{pmax}} \frac{1}{V_{pmax}} \times 100\%, \text{ or } [V_{pavg} - V_{pmin}) \times 100\%, \text{ whin}$ $V_{pmax} = \frac{1}{V_{pmax}} \frac{1}{V_{pmax}} \times 100\%, \text{ or } [V_{pavg} - V_{pmin}) \times 100\%, \text{ or } [V_{pavg} - V_{pmin}] \times 100\%, \text{ or } [V_{pavg}$ ver is gre

V_{pmin} is the minimum pixel voltage of any pixel at full bright

11. Uptotal = [(Vpmax - Vpmin)/Vpavg] x 100%,

12. Upadj = MAX [| (Vp(n) - Vp(n+1) | / Vp(n)] x 100%, where

Upadj is the nonuniformity in percent between adjacent pixels for. Jackground

13. V_d is the pixel amplitude value of V_{OUT} for a dark signal defined a ack do ...nent with LEDs turned off

 $14.U_d = V_{dmax} - V_{dmin}$, where

 V_{dmax} is the maximum pixel voltage of any dark pixel v the LEDs turn V_{dmin} is the minimum pixel voltage of any dark pixel with LEDs turned to the control of the

LEDs ture ea off

15.MTF = [(V_{max} - V_{min})/(V_{max} + V_{min})] x 100%, where V_{max} is the maximum output voltage at the spe

nair: nch (lp/in)

V_{min} is the minimum output voltage at the spraied lp/in

16. For information only.

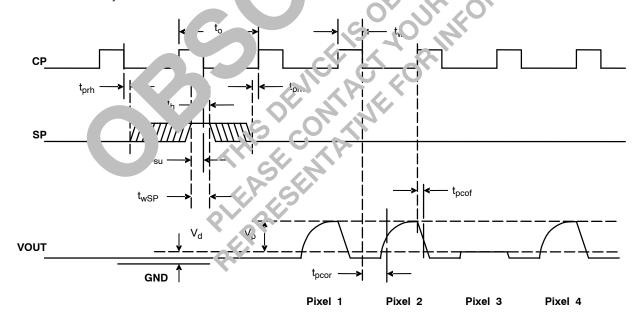


Figure 3. Timing Diagram

DESCRIPTION OF OPERATION

Functional Description

The NOM03A6-AY17G module consists of 13 contact image sensors, each with 96 pixel elements, that are cascaded to provide 1248 photo-detectors with their associated multiplex switches and double-buffered digital shift register that controls its sequential readout. A buffer amplifies the video pixels from the image sensors and output the analog video signal of the module as shown in Figure 2. In operation, the sensors produce an analog image pixel signal (or video signal) proportional to the exposure on the corresponding picture elements on the document. The VOUT signal outputs 1248 pixels for each scan line. The first bit shifted out from VOUT during each scan represents the first pixel on the connector end of the module.

A pictorial of the NOM03A6–AY17G cross section view is shown in Figure 4. Mounted in the module is a one-to-one graded-index micro lens array that focuses the scanned document image onto the sensing plane. Illumination is accomplished by means of an integrated LED light source, An internal reflector helps illuminate the document more completely, eliminating shadows caused by wrinkles in the paper. All components are housed in a small plastic lining, which has a glass cover. The top surface of the glass ac the focal point for the object being scanned? imaging array, micro lens assembly and L D light's rce from dust.

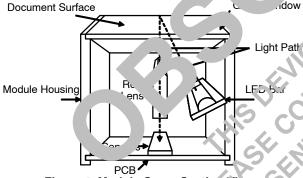


Figure 4. Module Cross Section View

Connector Pin Out Description

Connections to the module are via a 2.4x14 5 0mm 10-pin connector (ECE part number EBW-PK23-P010L2-3Z) located at one end of the module as she vn in the package drawing on page 8. The location of pin number 1 is indicated on the package drawing.

Scanner Applications

A typical use of the NOM03A6-AY17G module in scanner applications is shown in Figure 6. The document to be digitized is fed into the scanner where a sensor detects its presence. The scanner then operates the motor to move the paper under the contact image sensor module. The module illuminates the paper with internal LEDs and the image sensor pixel array detects the amount of reflected light and simultaneously measures a full line of pixels which are sampled and transferred to a FIFO for storage and conversion to a parallel output format. Once the pixel line is processed, the motor advances the paper and the next scan line is captured.

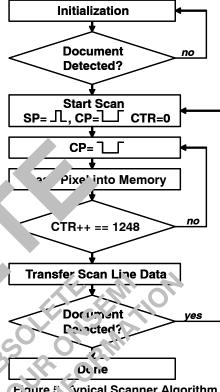


Figure 5 Typical Scanner Algorithm

Figure 5 outlines the basic steps in the scanner control sequence. First the circuits are initialized and the scanner weis for a document to be detected, usually by a paper sensing switch. Then a start pulse and clock pulse are supplied to capture a line image. At the next clock pulse the fast pixel value appears on the output. The pixel can be stored in a local line buffer memory. Subsequent clocks cause the remaining pixels to be shifted out and stored in the line buffer. Once the complete line has been shifted out it can be transferred to the host application and the system advances the paper and the line scan process repeats until the paper sensing switch indicates the document has passed completely through the scanner.

Device Marking and Barcode Description

Each module is marked with a tag that contains the part number, a number combining the manufacturing date code and serial number and a barcode. The barcode presents the date code and serial number in Interleave 2 of 5 barcode format as follows

YYMMSSSSSS

where YY is the year,

MM is the month, and

SSSSS is the serial number.

Glass Lens Care

Precautions should be taken to avoid scratching or touching the glass lens. The glass lens may be cleaned with alcohol.

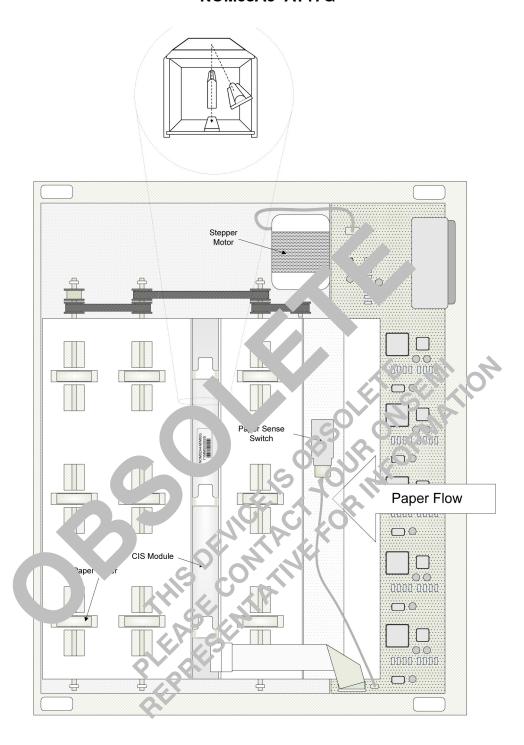
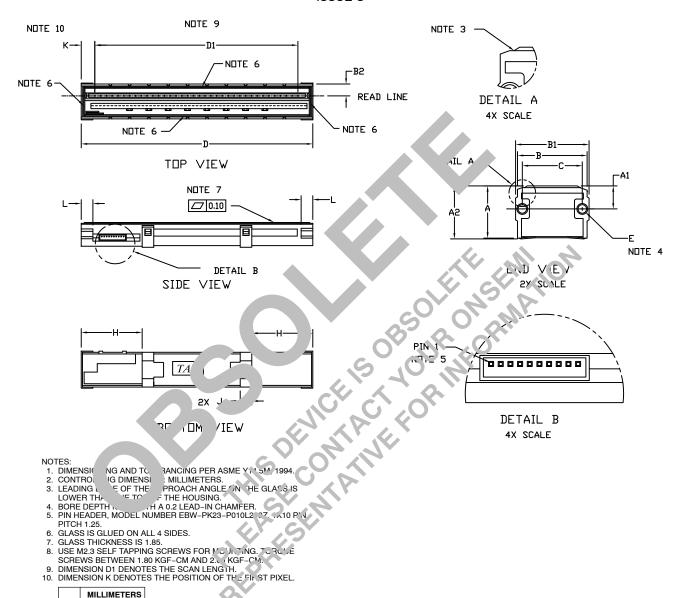


Figure 6. Typical Scanner Assembly

PACKAGE DIMENSIONS

IMAGE SENSOR MODULE A6

CASE MODAF **ISSUE O**



NOTES:

- NOTES:

 1. DIMENSI(NG AND TC RANCING PER ASME YILLS M. 1994.

 2. CONTROL IG DIMENSI : MILLIMETERS.

 3. LEADING L FOF THE PROACH ANGLE IN THE GLASS IS LOWER THE TO FITTE HOUSING.

 4. BORE DEPTH HAD 0.2 LEAD IN CHAMFER.

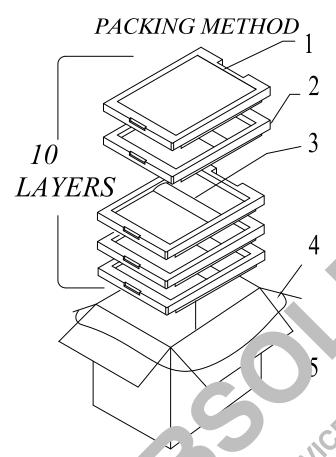
 5. PIN HEADER, MODEL NUMBER EBW-PK23-P010L2 27 IN 19 N.
- PITCH 1.25.

 6. GLASS IS GLUED ON ALL 4 SIDES.

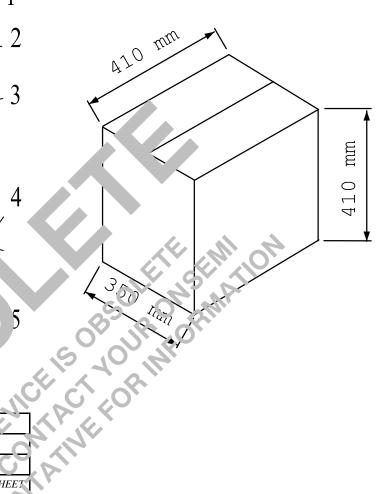
- 6. GLASS IS GLUED ON ALL 4 SIDES.
 7. GLASS THICKNESS IS 1.85.
 8. USE M2.3 SELF TAPPING SCREWS FOR NOTING, TORCY SCREWS BETWEEN 1.80 KGF-CM AND 2.0 KGF-CM.
 9. DIMENSION DI DENOTES THE SCAN LENG IH.
 10. DIMENSION K DENOTES THE POSITION OF THE FIRST PIXEL.

	MILLIMETERS			
DIM	MIN	MAX		
Α	13.00	14.00		
A1	6.70	7.70		
A2	13.20	14.20		
В	17.70	18.30		
B1	18.70	19.30		
B2	5.50	6.50		
С	15.20	15.80		
D	119.20	120.20		
D1	104.0	0 REF		
E	2.10	2.30		
Н	34.80	35.80		
J	5.70	6.30		
K	6.00	8.00		
1	6 00 BFF			

PACKING DIMENSIONS



PACKING COMPLETE



NO.	NAME	MATERIAL
1	Shockpr	LPE C
2	Packii Tray	POLYFOAM.
3	Conduct ctricit neet	PE + CONDUCTIVE SHEET
4	Waterproof Bag	PE
5	Packing Box-Carton	KRAFT PAL FR

The products described herein (NOM03A6-AY17G), is covered by one or more of the following U.S. patent; 6,025,935. There may be other patents pending.

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